

Datasheet

SPRINT 700 Subsea AAINS



Description

SPRINT 700 is a combined solid state Attitude and Heading Reference System (AHRS) and SPRINT Acoustically Aided Inertial Navigation System (AAINS).

The instrument is comprised of three high grade, highly reliability, commercially available, Ring Laser Gyros (RLG) and accelerometers. The sensors are also the standard for commercial aviation with a proven 15+ year track record.

The AHRS requires no external aiding and can settle in 5 minutes or less in dynamic conditions. INS adds advanced Aided Inertial Navigation that runs concurrently with the AHRS algorithm.

This dual algorithm capability is unique in the market and allows for dual use from one inertial instrument, e.g. AHRS for ROV, INS for Survey.

On-board data storage and backup battery functionality ensures continued operation and no data-loss even if communications or external power is lost.

SPRINT INS interfaces to aiding sensors such as a USBL or LBL transceivers, a DVL, pressure sensor and sound speed. Power-pass through to aiding sensors is supported to ease integration.

SPRINT has a proven track record spanning 10 years in the field in diverse applications from ROV guidance and autopilot to demanding survey applications such as multibeam Out Of Straightness surveys and sparse-LBL using tightly coupled 6G acoustics.

The instrument is available in 4,000 and 6,000 metre depth ratings and as an OEM version and is one of the smallest form factor subsea inertial instruments available.

Applications Include

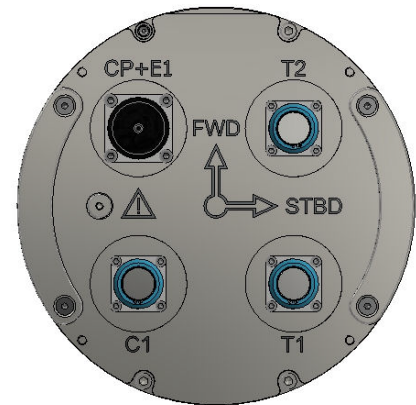
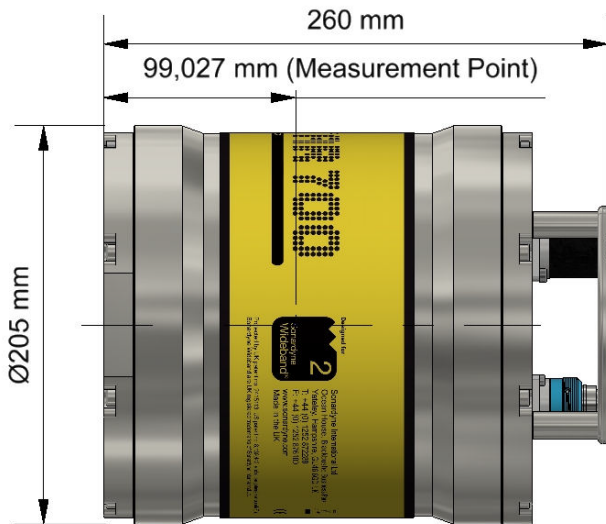
- ROV and Towfish Positioning
- Hydrographic Survey
- Offshore Construction
- As-Laid and Out of Straightness
- Multibeam Survey
- Touchdown Monitoring
- Structure Placement

Key Features

- Single box solution for motion sensor, gyrocompass and AAINS
- SPRINT provides concurrent AHRS and AAINS capability for dual use
- 0.08° (AHRS) to 0.02° (INS) secant latitude heading accuracy
- 0.01° roll and pitch accuracy
- 5 minute AHRS settling time
- Fast follow up speed of 900°/sec
- MTBF inertial sensors (RLG and Accelerometer) > 400,000 hours
- Choice of depth ratings: 4,000 and 6,000 metres
- Choice of connectors: Seacon (standard) or Seacnet® (for use with FMC Schilling Robotics ROV)
- Transport approved rechargeable lithium battery back-up as standard
- Minimum internal memory of 8 GB allows post processing and remote diagnostics
- Ethernet interface

Specifications

SPRINT 700 Subsea AAINS



Feature	SPRINT	Type 8253-xxx	Type 8253-xxx
Depth Rating		4,000 metres	6,000 metres
Physical	Size (Diameter x Length)	Ø205 x 260 mm	Ø205 x 280 mm
	Weight in Air/Water*	18.5/11.5 kg	22/14 kg
	Mechanical Construction	Titanium	Titanium
	Connectors	4 x Seacon	4 x Seacon
	Performance	Heading Accuracy	0.08° (AHRS), 0.02° (INS) Secant Latitude
	Roll and Pitch Accuracy	0.01°	
	Settle Time	<5 minutes in dynamic conditions (AHRS), Instantaneous (INS)	
	INS Aiding Supported	USBL, Depth, DVL, Zero Velocity, Manual Position, LBL (range & position), GNSS	
	USBL Aided	4.5 x precision improvement over USBL	
	USBL and DVL Aided	6 to 13 x precision improvement over USBL	
	DVL Aided Accuracy	0.08% position error for distance travelled (3 rd party DVL) 0.06% position error for distance travelled (Sonardyne Syrinx DVL)	
	DVL Aiding Loss/Drift	<0.5 m over 1 min, 2 m over 2 mins (CEP50)	
	Station Keeping	<1 m over 24 hours	
	LBL & DVL Aided Accuracy	3 cm confined area, 20 cm wide area (dynamic)	
	'Synthetic' LBL Aided Accuracy	<15 cm @ 200 m distance to single transponder	
Environmental	Temperature	-20 to +55°C (operating), -20 to +60°C (storage)	
	Shock Rating	22 g, 11 ms half sine	
Power	Power Requirement	20–50 V dc, 15 W nominal, 35 W max	
	Back Up Battery Type/Life	Li-ion/5 minutes	
Data/Comms.	Data Storage	8 GB internal memory	
	Digital Ports/Protocol	up to 4 digital Ports/RS232 or RS485	
	Other Ports	1 x Ethernet, 4 Triggers	
	Output Rate	Up to 100 Hz	
	Output Telegrams	Industry standard AHRS/INS telegrams including acceleration and rotation rates**	

*Estimated Weights

**Specific outputs may be limited below quoted performance for reasons of export classification and control and should not be used as IMU data.